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## International Workshop on Automotive Radar for Fully Automated Driving

Wednesday, 16<sup>th</sup> September 2020, 08.00 – 12.00 CEST (UTC+2), online (links will be provided by e-mail)

#### 08:00 Session 1: General aspects on automated and connected driving (online live)

Welcome address Stefan Mengel, Division "Electronics and Autonomous Driving", German Federal Ministry for Education and Research (BMBF)

Push & pull in digitalization Felix Govaers, Fraunhofer FKIE

Future urban mobility Klaus Bogenberger, Technical University of Munich

09:30 Questions and discussions in virtual marketplace (online live in four rooms, video files of the presentations will be provided on 14 <sup>th</sup> September)			
Session 2: New radar architectures and signal processing	Session 3: New MMICs, antenna and packaging concepts		Session 5: Radar testing and verification
Rudolf Lachner, Infineon Technologies AG Automotive radar building blocks Benjamin Nuß, Karlsruhe Institute of Tech-	Jan Schöpfel, Ruhr University Bochum SiGe transceiver chipsets for arbitrarily modulated radar at 77 GHz	Thomas Binzer, Robert Bosch GmbH Cooperative sensor networks: chances and challenges	Florian Baumgärtner, Daimler OTA test scenarios for automated driving
nology  OFDM radar for automotive applications	Ahmad Mushtaq, Silicon Radar Cascadable radar MMIC for massive MIMO-applications	Benedikt Meinecke, Johannes Schlichen- maier, University of Ulm Coherent and incoherent sensor net- works Markus Gardill, University of Würzburg Radar architectures and signal pro-	Thomas Walter, University of Applied Sciences Ulm Radar target simulator
Simon Stephany, University of Ulm Digitally modulated radar and 4x8 MIMO demonstrator	Thanh Duy Nguyen, IZM, Jue Chen, Schweizer, and Jonathan Mayer, Karls- ruhe Institute of Technology Panel level packaging and system in board technologies for conformal radar frontend		Sebastian Graf, dSPACE, Andreas Löffler, Continental Raytracing simulations in automotive
Martin Kunert, Robert Bosch GmbH High resolution fast chirp imaging radar for automotive applications		cessing for autonomous driving Cristian Grozea, Fraunhofer Fokus Camera-radar-fusion for safe driving in urban environment	radar tests Sevda Abadpour, Karlsruhe Institute of Technology
Maria Gonzalez, Fraunhofer FHR Sparse MIMO arrays and high-resolution estimation using compressed	Christian Tschoban, IZM MIMO-based module with integrated antennas for autonomous driving		Radar channel simulation  Matthias Hein, TU Ilmenau  Virtual verification and validation of au-

#### 10:30 Session 6: Virtual lab with demonstrators (online live in different rooms)

An all-digital 4x4 MIMO automotive radar prototype based on an RFSoC Simon Stephany, University of Ulm

Fast chirp sequence 4x16 TDM MIMO imaging radar demonstrator for automated driving applications *Martin Kunert, Robert Bosch GmbH* 

Printed circuit board technology enables direct embedding of MMIC and conformal antenna configuration for automotive radar application *Jue Chen, Schweizer Electronic AG* 

Automotive radar sensor testing using real-time ray tracing  $Sebastian\ Graf,\ dSPACE$ 

Automotive radar OTA test setup with target simulator and mechanical positioner Bastian Hellweg, dSPACE, Ralf Stephan, TU Ilmenau

A 77 GHz radar demonstrator for arbitrary digital modulation schemes
Benjamin Nuß, Karlsruhe Institute of Technology, Jan Schöpfel, Ruhr University Bochum

### 11:30 Session 7: Panel discussion and closing remarks (online live)

Panel discussion Stefan Mengel, Division "Electronics and Autonomous Driving", German Federal Ministry for Education and Research (BMBF), Rudolf Lachner, Infineon, Martin Kunert, Robert Bosch GmbH, Frank Gruson, Continental, Holger Meinel, Independent ADAS Consultant

Closing address Stefan Mengel, Division "Electronics and Autonomous Driving", German Federal Ministry for Education and Research (BMBF)

Details and Registration: <a href="www.ihe.kit.edu/workshop.php">www.ihe.kit.edu/workshop.php</a>
Contact: <a href="mailto:thomas.zwick@kit.edu/workshop.php">thomas.zwick@kit.edu/workshop.php</a>



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tomotive radar in the installed state